



Operating Instructions

Ultrasonic proximity switch with one switched output and IO-Link interface

Ics+340/F lcs+600/F

### **Product description**

The lcs+ sensor offers a non-contact measurement of the distance to an object which must be positioned within the sensor's detection zone. The switched output is set conditional upon the adjusted detect distance.

Via the Teach-in procedure, the detect distance and operating mode can be adjusted. One LED indicates operation and the state of the switched output.

The lcs+ sensors are IO-Link-capable in accordance with IO-Link specification V1.0.

#### Safety instructions

- Read the operating instructions prior to start-up.
- Connection, installation and ad-

justments may only be carried out by qualified staff.

■ No safety component in accordance with the EU Machine Directive

# Use for intended purpose only

lcs+ ultrasonic sensors are used for non-contact detection of objects.

#### Installation

- Mount the sensor at the place of
- Connect a connection cable to the M12 device plug.

### Start-up

- Connect the power supply.
- Carry out sensor adjustment in accordance with the diagram.

2 • 1 3 • 5 • 4	1	colour
1	+U <sub>B</sub>	brown
3	-U <sub>B</sub>	blue
4	F	black
2	-	white
5	Sync	grey

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cables

# Factory setting

- Switched output on NOC.
- Detect distance at operating range.

Three operating modes are available for the switched output:

- Operation with one detect point The switched output is set when the object falls below the set detect point.
- Window mode

The switched output is set when the

■ Two-way reflective barrier The switched output is set when the object is between sensor and fixed reflector.

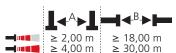


Fig. 2: Assembly distances

object is within the set window.

Maintenance microsonic sensors are maintenance-



# Notes

Synchronisation

of max 10 sensors

sensor surface.

■ The sensors of the lcs+ family have a blind zone, within which a distance measurement is not possi-

If under multiple sensor operation

the assembly distance falls below the

values shown in Fig. 2, the internal

synchronisation should be used. For

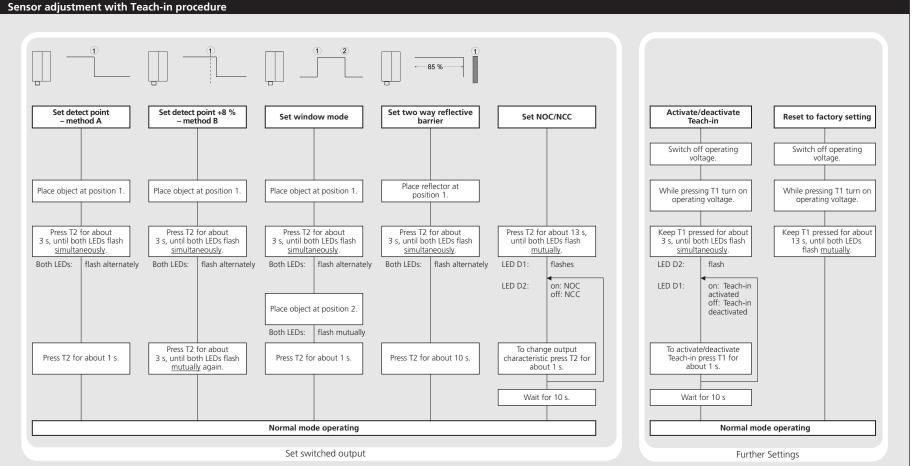
this purpose interconnect each pin 5

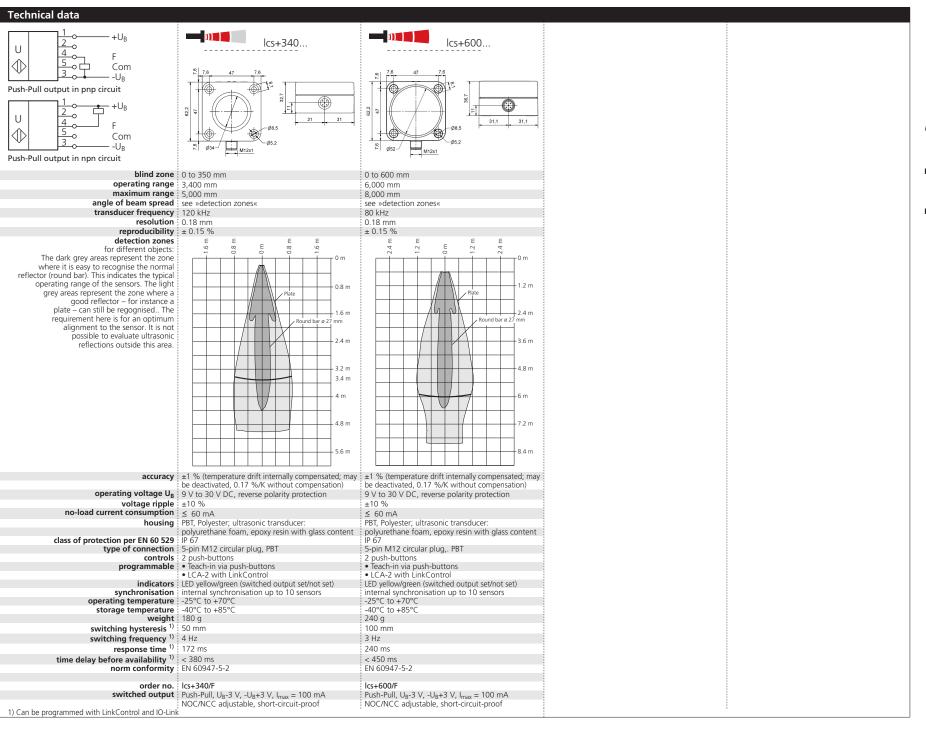
free. In case of excess caked-on dirt

we recommend cleaning the white

- The lcs+ sensors are equipped with an internal temperature compensation. Due to the sensors self heating, the temperature compensation reaches its optimum working-point after approx. 30 minutes of operation.
- In the normal operating mode, an illuminated yellow LED signals that the switched output is switched through.
- The lcs+ sensors have a push-pull switched output.
- In the »Two-way reflective barrier« operating mode, the object has to be within the range of 0-85 % of the set distance.
- In the »Set detect point method A« Teach-in procedure the actual distance to the object is taught to the sensor as the detect point. If the object moves towards the sensor (e.g. with level control) then the taught distance is the level at which the sensor has to switch the output.
- If the object to be scanned moves into the detection area from the side, the »Set detect point +8 % method B« Teach-in procedure should be used. In this way the switching distance is set 8 % further than the actual measured distance to the object. This ensures a reliable switching distance even if the height of the objects varies slightly.

# Operating modes





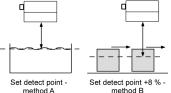


Fig. 4: Setting the detect point for different directions of movement of the object

- The sensor can be reset to its factory setting (see »Further settings«).
- Using the LinkControl adapter (optional accessory) and the LinkControl software for Windows, all Teach-in and additional sensor parameter settings can be optionally undertaken.

#### Sensor adjustment in IO-Link mode

The lcs+ sensors are IO-Link-capable in accordance with IO-Link specification V1.0

#### **Pointer**

■ In IO-Link mode LinkControl is not available.

# **Process data**

The lcs+ cyclically transmits the measured distance value with a resolution of 1 mm and the logical state of the switched output.

#### Service data

The following sensor parameters may be set via IO-Link interface using the IO-Link device description (IODD).

#### Detect point 1

**IO-Link data** 

The switched output is activated

when the distance to an object is smaller than the present detect point.

#### Return detect point 1

The switched output is reactivated when the distance to an object is greater than the present return detect point (detect point + hysteresis).

#### Pointer

01

baud rate : COM 2 (38.400 Bd)

service data sensor specific index format access range (dez)

detect point 1 0x40 UINT16 R/W

detect point 2 0x42 UINT16 R/W

maximum range 0x45 UINT16 R/W

measurement filter 0x48 UINT8 R/W

set NOC/NCC 0x47 UINT8 R/W

filter strength 0x49 UINT8 R/W

switch-on delay 0x4B UINT8 R/W

return detect point 2 0x43 UINT16 R/W

foreground suppression :0x44 | UINT16 | R/W

Teach-in via push-button T1/T2 0x46 UINT8 R/W

emperature compensation | 0x4A | UINT8 | R/W

detection zone sensitivity 0x4C UINT8 R/W

observe Index

distance value :0x51 :UINT16:R

echo quality 0x50 UINT16 R

multiplex mode device addressing 0x4D UINT8 R/W

multiplex mode highest address Ox4E UINT8 R/W

interference noise suppression 0x4F UINT8 R/W

system commands Index

Teach-in detect point 0x02

reset to factory settings :0x02

Teach-in detect point + 8 % 0x02

Teach-in window mode detect point 1 :0x02

Teach-in window mode detect point 2 0x02

Teach-in two way reflective barrier 10x02

content of process data Bit 0: logical state of switched output,

physical laver

SIO mode support yes

service data IO-Link specific lindex

min cycle time 43 ms

format of process data 16 Bit, R, UNI16

Vendor name 0x10

Product name 10x12

Vendor text :0x11

Product ID: 0X13

Product text 0x15

■ The return detect point 1 must always be greater than the detect point 1.

# Detect point 2, return detect point 2

By programming these two detect distances to a value smaller than the actual maximum distance the window mode is activated. The window lies between detect point 1 and detect point 2.

Bit 1-15: distance value with 1 mm resolution

access value

1) > 58.162: window mode deactivated

lcs+

340/F

R

lcs+340...

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(0-4.256 (0-1.050 mm)

0: NCC, 2: NOC

0-4: F00 - F04

0-9: P00 - P09

0-20: 0-20 s

1-10

161

162

163

164

165

166

1) Distance values as e.g. detect points are given as a multiple of the internal measurement resolution = 0.172 mm (example: 2.038 \u220b 350 mm)

access value

W

W

W

W

W

access

0: deactivated, 2: activated

0: deactivated, 2: activated

1: high, 2: standard, 3: low

0: deactivated, 2: activated

2.038-29.098 (350-4.998 mm)

return detect point 1 0x41 UINT16 R/W 2.044-29.104 (351-4.999 mm) 0x41 UINT16 R/W 3.499-46.570 (601-7.999 mm)

2.049-58.214 (352-4.999 mm)<sup>1)</sup> 0x42 UINT16 R/W

2.044-58.214 (351-4.998 mm)<sup>1)</sup> 0x43 UINT16 R/W

29.110-58.162 (5.000-9.990 mm); 0x45; UINT16; R/W

0-11: 0: sync, 11: deactivated 0x4D UINT8 R/W

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#### Pointer

■ The return detect point 2 must always be smaller than the detect point 2.

#### Foreground suppression

Spurious reflections, caused by objects in the foreground of the sensor may be blocked out by the foreground suppression.

#### Pointer

60,8 ms COM 2 (38.400 Bd)

index

0x10

0x11

0x12

0X13

0x15

16 Bit, R, UNI16

0x40 UINT16 R/W

0x44 :UINT16:R/W

0x46 UINT8 R/W

0x47 UINT8 R/W

0x48 UINT8 R/W

0x49 UINT8 R/W

0x4A UINT8 R/W

0x4B LIINT8 R/W

0x4E UINT8 R/W

0x4F UINT8 R/W

0x4C UINT8

Index

0x02

0x02

0x02

0x02

0x02

0x02

Index

0x51 :UINT16:R

0x50 UINT16 R

Bit 0: logical state of switched output.

₽

index format access range (dez)

1) > 58.162: window mode deactivated

:R/W

W

: W

:W

:w

W

:w

access

Bit 1-15: distance value with 1 mm resolution

access value

:Ics+

600/F

- The object in the foreground can cause multiple reflections that lead to invalid measurement.
- The object in the foreground must not cover the sensor in a way that the detection zone is influenced.

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Ultraschall-Sensor

:0-7.295 (0-1.800 mm)

0: NCC. 2: NOC

0-4: F00 - F04

0-9: P00 - P09

0-20: 0-20 s

1-10

161

162

163

164

165

166

access value

3.493-46.564 (600-7.998 mm)

3.505-58.214 (602-7.999 mm)<sup>1</sup>

3.499-58.214 (601-7.998 mm)

46.576-58.162 (8.000-9.990 mm)

0: deactivated, 2: activated

0: deactivated, 2: activated

1: high, 2: standard, 3: low

0: deactivated, 2: activated

0-11: 0: sync, 11: deactivated

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#### Maximum range

The value specifies the maximum measurement range.

#### Teach-in via push-buttons T1/T2

The push-buttons can be locked/unlocked for the Teach-in procedures.

#### Set NOC/NCC

The NCC or NOC output function can be present for the switched output.

### Measurement filter

lcs+ ultrasonic sensors provide for a choice of 5 filter settings:

- F00 (no filter)
  Each ultrasonic measurement acts in an unfiltered manner on the output.
- F01 (standard filter)

On the object continuously approaching the sensor, the ongoing interval is immediately taken on and the output correspondingly activated. The effect of the object abruptly moving away from the sensor is for the existing distance to be saved for a retaining time dependent on the filter strength and for the switched output state to be maintained.

■ F02 (Average value filter)
Forms the arithmetic mean across a number of measurements. The output is activated in keeping with the average value. The number of measurements, from which the average value is formed, depends

on the selected filter strength.

■ F03 (foreground filter)

This filter reacts very fast on sensor close measurement values and gives a straightened output on this sensor close level. Disturbances from objects in the background or momentary loss of echoes from the object to be detected are filtered out.

■ F04 (background filter)

This filter reacts very factors

This filter reacts very fast on sensor far measurement values and gives a straightened output on this sensor far level. Disturbances from obstacles in front of the object to be detected are filtered out.

#### Filter strength

A filter strength between 0 – weak filter effect – and 9 – pronounced filter effect – can be selected for each measurement filter.

### Temperature compensation

The temperature compensation improves the measurement accuracy at changing ambient temperature and may be deactivated.

#### **Pointer**

■ The measurement accuracy amounts to 0,17 %/K change of temperature without compensation.

#### Switch-on delay

If the switch-on delay is activated, the switched output will not be set before the programmed time once the measurement value falls below the set detect point. If the measurement value increases to the detect point again, the switched output will be reset after 50 % of the programmed on-delay time.

# **Detection zone sensitivity**

The size of the detection zone can be varied in three steps.

# Synchronisation and multiplex in IO-Link mode

As in SIO mode up to 10 sensors can be synchronised by interconnecting the sync-channel (Pin 5) of each sensor. Additionally the multiplex mode is available.

#### Multiplex mode device address

In multiplex mode for every sensor connected via the sync-channel a unique device address has to be set. The sensors then perform there measurement in increasing order of the device addresses. With multiplex address »0« the sensors work synchronous, with address »11« synchronisation/multiplex is disabled.

#### **Pointer**

In multiplex mode the response time of each sensor extends corresponding to the number of connected sensors.

# Multiplex mode highest address

To optimise the multiplex speed the highest assigned device address may be set instead of the default value »10«.

### Interference noise suppression

This filter keeps the state of the output for the time a ultrasonic interference noise, e.g. leaking compressed air, makes a measurement impossible

#### Pointer

■ The Interference noise suppression filter extends the measurement cycle of the sensor and for this it's response time.

#### **Echo quality**

To simplify the adjustment of the sensor towards the measurement object the echo quality can be observed. The value gives back the strength of the reflected echo.

# **System commands**

With 6 system commands the following settings may be carried out:

- Teach-in detect point.
- Teach-in detect point +8 %.
- Teach-in window mode detect point 1.
- Teach-in window mode detect point 2.
- Teach-in two way reflective barrier.
- Reset sensor to factory settings.

#### IODD file

The latest IODD file you will find on the internet under www.microsonic.de/en/IODD.

For further informations on IO-Link see www.io-link.com.



